## **Golden Ding Series Analog Servo Drives**



# Peak Current 12 A Continuous Current 6 A Supply Voltage 20 - 80 VDC



#### **Description**

The CAB12A80 PWM servo drive is designed to drive brushless and brushed DC motors at a high switching frequency. The CAB12A80 is fully protected against over-voltage, over-current, over-heating, and short-circuits. A single digital output indicates operating status. The drive interfaces with digital controllers that have analog +/-10V output.

See Part Numbering Information on last page of datasheet for additional ordering options.

#### **Features**

- Four Quadrant Regenerative Operation
- Direct Board-to-Board Integration
- Lightweight
- High Switching Frequency
- Wide Temperature Range
- High Performance Thermal Dissipation

- Differential Input Command
- Digital Fault Output Monitor
- Current Monitor Output
- Single Supply Operation
- Compact Size
- ➤ High Power Density

#### HARDWARE PROTECTION

- Over-Voltage
- Over-Current
- Over-Temperature
- Short-circuit (phase-phase)
- Short-circuit (phase-ground)

#### **INPUTS/OUTPUTS**

- Digital Fault Output
- Digital Inhibit Input
- Analog Current Monitor
- Analog Command Input
- Analog Current Reference

#### **FEEDBACK SUPPORTED**

Hall Sensors

#### **MODES OF OPERATION**

Current

#### COMMUTATION

Trapezoidal

#### **MOTORS SUPPORTED**

- Three Phase (Brushless)
- Single Phase (Brushed, Voice Coil, Inductive Load)

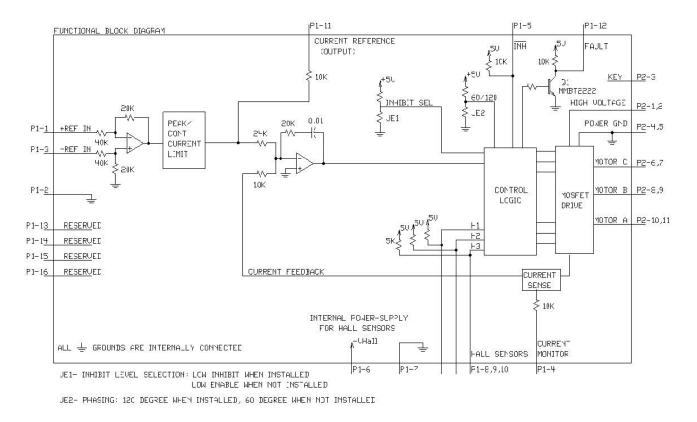
#### **COMMAND SOURCE**

±10 V Analog

**CAB12A80** 



#### **BLOCK DIAGRAM**



#### HARDWARE SETTINGS

#### Jumper Settings

Jumpers are SMT, 0 ohm resistors located on the underside of the drive PCB. By default, the drive is configured with the jumpers installed. Typical drive operation will not require the jumpers to be removed. Please contact the factory before jumper removal.

Jumpe	Description	Configuration	
	SMT Jumper(0Ω Resustor)	Not Installed	Installed
JE1	Inhibit logic. Sets the logic level of inhibit pins. Labeled JE1 on the PCB of the drive.	Low Enable	Low Inhibit
JE2	Hall sensor phasing. Selects 120 or 60 degree commutation phasing. Labeled JE2 on the PCB of the drive.	60 degree	120 degree

#### Notes:

Any damage done to the drive while performing these modifications will void the product warranty.It is recommended to contact AMC China's technical staff before setting of JPE1 and JPE2.

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### **SPECIFICATIONS**

Power Specifications					
Description	Units	Value			
DC Supply Voltage Range	VDC	20 - 80			
DC Bus Under Voltage Limit	VDC	18			
DC Bus Over Voltage Limit	VDC	88			
Maximum Peak Output Current <sup>1</sup>	Α	12			
Maximum Continuous Output Current	Α	6			
Maximum Continuous Output Power	W	456			
Maximum Power Dissipation at Continuous Current	W	24			
Minimum Load Inductance (Line-To-Line) <sup>2</sup>	μH	100			
Internal Bus Capacitance <sup>3</sup>	μF	33			
Low Voltage Supply Outputs	-	+6 VDC (30 mA)			
Switching Frequency	kHz	31			
Control Specifications					
Description	Units	Value			
Command Sources	-	±10 V Analog			
Feedback Supported	-	Halls			
Commutation Methods	-	Trapezoidal			
Modes of Operation	-	Current			
Motors Supported	-	Three Phase (Brushless), Single Phase (Brushed, Voice Coil, Inductive Load)			
Hardware Protection	-	Invalid Commutation Feedback, Over Current, Over Temperature, Over Voltage Short Circuit (Phase-Phase & Phase-Ground)			
Mechanical Specifications					
Description	Units	Value			
Size (H x W x D)	mm	127 x 77.5 x 44.5			
Operating Temperature Range	°C (°F)	0 - 75 (32 - 185)			
StorageTemperature	°C (°F)	-40 - 85 (32 - 185)			
Relative Humidity		0 - 90% Non-Condensing			
P1 Connector		16 Pin, pitch 2.54 mm connector			
P2 Connector		8Pin pitch 5.08 mm Pluggable terminal block			

#### Notes

- 1. Maximum duration of peak current is ~2 seconds. Peak RMS value must not exceed continuous current rating of the drive.
- 2. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
- 3. Requires a 100µF/100V electrolytic capacitor near the P2 Power Connector between High Voltage and Power Ground pins.



#### **PIN FUNCTIONS**

P1 Signal Interface Definitions						
Connector information		16 Pin, pitch 2.54 mm connector				
Matching Part No. Connector Remark		Molex: P/N 22-01-3167 (Housings) and P/N 08-50-0114 (CRIMP TERMINAL)				
		Connectors need to be ordered separately				
Pin	Signal	Description				
1	+REF IN	Differential Reference Input (±10 V Operating Range, ±15 V Maximum Input)				
2	SIGNAL GND	Signal Ground				
3 -REF IN		Differential Reference Input (±10 V Operating Range, ±15 V Maximum Input)				
4 CURRENT MONITOR		Current Monitor. Analog output signal proportional to the actual current output. Polarity is reversed from command voltage. Scaling is 4 A/V. Measure relative to signal ground.				
5 INHIBIT IN		TTL level (+5 V) inhibit/enable input. Leave open to enable drive. Pull to ground to inhibit drive. Inhibit turns off all power devices.				
6	+V HALL OUT	Low Power Supply For Hall Sensors (+6 V @ 30 mA). Referenced to signal ground. Short circuit protected.				
7	SIGNAL GND	Signal Ground				
8	HALL 1					
9	HALL 2 <sup>1</sup>	Single-ended Hall/Commutation Sensor Inputs (+5 V logic level)				
10	HALL 3	Measures the command signal to the internal current-loop. This pin				
11	CURRENT REFERENCE	has a maximum output of ±7.45 V when the drive outputs maximum peak current. Measure relative to signal ground.				
12	FAULT OUT	TTL level (+5 V) output becomes high when power devices are disabled due to at least one of the following conditions: inhibit, invalid Hall state, output short circuit, over voltage, over temperature, power-up reset.				
13	RESERVED					
14	RESERVED	RESERVED				
15	RESERVED	- NEOLIVED				
16	RESERVED					
		5 RESERVED  13 RESERVED  11 CURRENT REFERENCE  9 HALL B  7 SIGNAL GND  1 +REF IN  2 SIGNAL GND  4 CURRENT MONITOR  4 CURRENT MONITOR  8 HALL A  10 HALL C  12 FAULT OUT  14 RESERVED  ESERVED				

1. For use with Single Phase (Brushed) motors, ground Hall 2 and only connect motor leads to Motor A and Motor B.

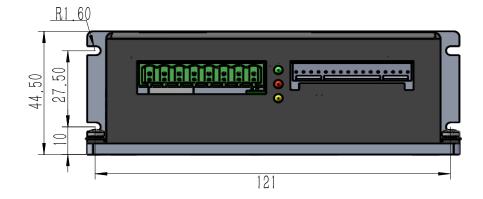
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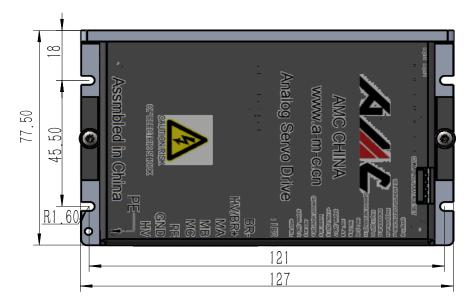


P2 Power Interface Definitions						
Connector information		nformation	8Pin pitch 5.08 mm Pluggable terminal block			
Match	ning	Part No.	KF2EDGK5.08			
Conne		Remark	Connectors need to be ordered separately			
Pin	Signal		Description			
1		HV	DC+ Power Input			
2		GND Power Ground (Common With Signal Ground).				
3	PE Protective ground (Connect motor cable shield)		Protective ground (Connect motor cable shield)			
4		MC Motor Phase W				
5	MB I		Motor Phase V			
6		MA	Motor Phase U			
7		HV/BR+	External braking resistor connection. Connect a resistor between BR+			
8		BR-	and BR			
		1HV	2GND 3PE 4MC 5MB 6MA 7HV/BR 88R-			



## **DIMENSIONS (mm)**

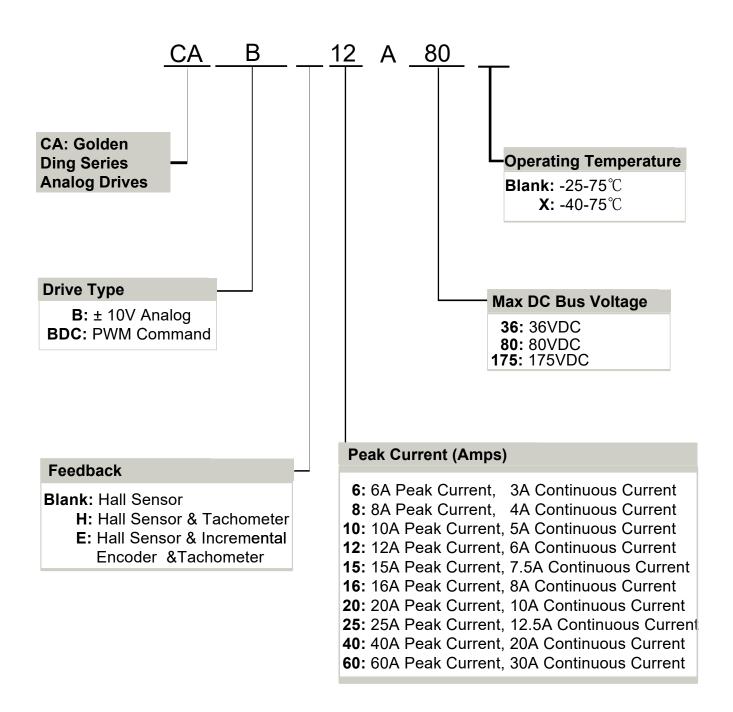








#### PART NUMBERING INFORMATION



Version 1.1